

Caepipe: Materials (1) - [HarmonicAnalysis.mod (D:\KPDDevelopment\Documents\Tutorials\HarmonicAnalysis)]

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#	Name	Description	Type	Density (lb/in3)	Nu	Joint factor	Yield (psi)	#	Temp (F)	E (psi)	Alpha (in/in/F)	Allowable (psi)
1	312	A312 TP316 (16Cr-12Ni-2Mo)	AS	0.289	0.3	1.00		1	325	30.3E+6	8.15E-6	20000
2								2	-200	29.7E+6	8.47E-6	20000
								3	-100	29.0E+6	8.75E-6	20000
								4	70	28.3E+6	9.11E-6	20000
								5	200	27.6E+6	9.34E-6	20000
								6	300	27.0E+6	9.47E-6	20000
								7	400	26.5E+6	9.59E-6	19300
								8	500	25.8E+6	9.70E-6	17900
								9	600	25.3E+6	9.82E-6	17000
								10	650	25.1E+6	9.87E-6	16700

Caepipe: Pipe Sections (3) - [HarmonicAnalysis.mod (D:\KPDDevelopment\Documents\Tutorials\Harmon...)]

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#	Name	Nom Dia	Sch	OD (inch)	Thk (inch)	Cor. Al (inch)	M.Tol (%)	Ins. Dens (lb/ft3)	Ins. Thk (inch)	Lin. Dens (lb/ft3)	Lin. Thk (inch)	Soil
1	6	6"	STD	6.6248	0.28			11	2.5591			
2	B	8"	STD	8.6248	0.322							
3	10	10"	STD	10.75	0.365							
4												

Caepipe: Loads (2) - [HarmonicAnalysis.mod (D:\KPDDevelopment\Documents\Tutorials\HarmonicAnaly...)]

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#	Name	T1 (F)	P1 (psi)	Specific gravity	Add. Wgt. (lb/ft)	Wind Load
1	L1	365	145	1.0		
2	L2	500	464	1.0		
3						

Step 2:

The harmonic load can be imposed as a Force (FX/FY/FZ) at a specified frequency and phase angle. You may be able to get more information on the harmonic loading (mass, rpm, etc.) from the manufacturer of the equipment.

For this Tutorial, the following assumptions are made.

1. Frequency of the rotating equipment = 14.5 Hz.
2. Force in Global Z Direction = FZ = 9000 lb.

The above parameters are entered for analysis by creating a "Data" type called "Harmonic Load" through Layout window > Misc > Data types... at Node 40. See snap shot below for details.

Harmonic load at node 40

Frequency (Hz)

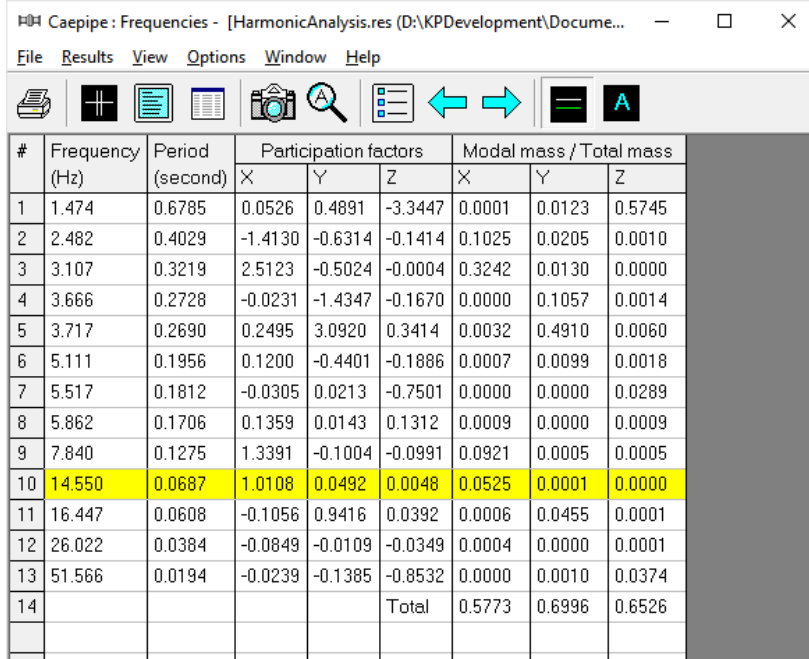
Phase (deg)

FX (lb) FY (lb) FZ (lb)

OK Cancel

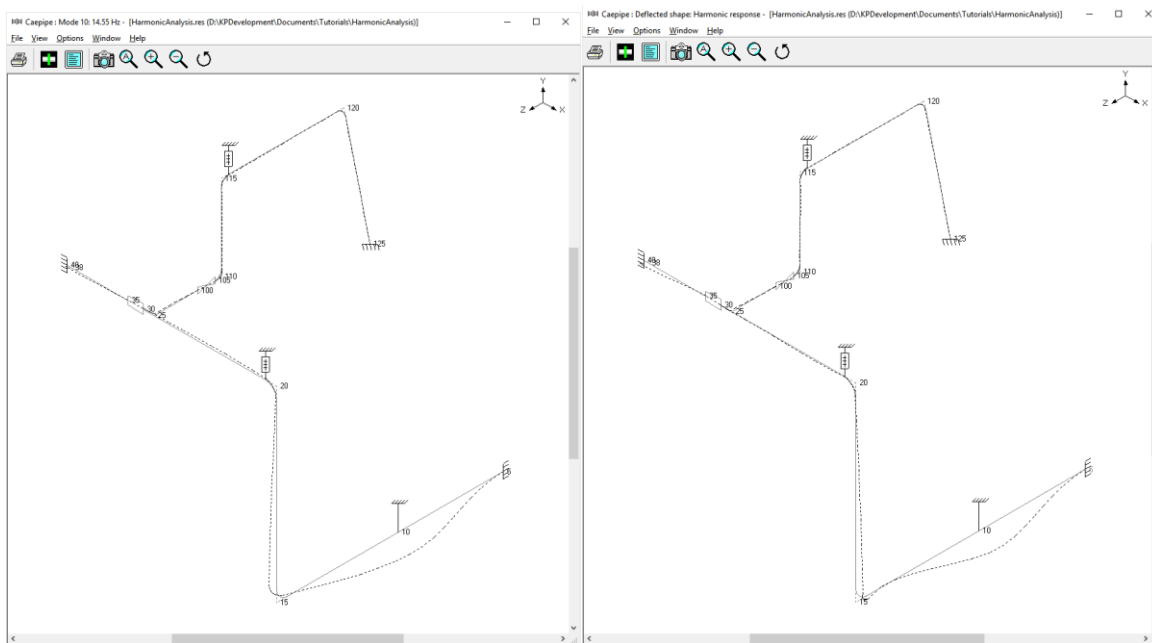
Step 7:

From the review of frequency results of CAEPIPE, it is noted that one of the natural frequencies of this piping system (i.e., frequency for Mode 10 shown in yellow highlight in the snap shot below) is close to the rotating equipment frequency of 14.5 Hz.



#	Frequency (Hz)	Period (second)	Participation factors			Modal mass / Total mass		
			X	Y	Z	X	Y	Z
1	1.474	0.6785	0.0526	0.4891	-3.3447	0.0001	0.0123	0.5745
2	2.482	0.4029	-1.4130	-0.6314	-0.1414	0.1025	0.0205	0.0010
3	3.107	0.3219	2.5123	-0.5024	-0.0004	0.3242	0.0130	0.0000
4	3.666	0.2728	-0.0231	-1.4347	-0.1670	0.0000	0.1057	0.0014
5	3.717	0.2690	0.2495	3.0920	0.3414	0.0032	0.4910	0.0060
6	5.111	0.1956	0.1200	-0.4401	-0.1886	0.0007	0.0099	0.0018
7	5.517	0.1812	-0.0305	0.0213	-0.7501	0.0000	0.0000	0.0289
8	5.862	0.1706	0.1359	0.0143	0.1312	0.0009	0.0000	0.0009
9	7.840	0.1275	1.3391	-0.1004	-0.0991	0.0921	0.0005	0.0005
10	14.550	0.0687	1.0108	0.0492	0.0048	0.0525	0.0001	0.0000
11	16.447	0.0608	-0.1056	0.9416	0.0392	0.0006	0.0455	0.0001
12	26.022	0.0384	-0.0849	-0.0109	-0.0349	0.0004	0.0000	0.0001
13	51.566	0.0194	-0.0239	-0.1385	-0.8532	0.0000	0.0010	0.0374
14					Total	0.5773	0.6996	0.6526

Due to closeness of Mode 10 frequency to the equipment frequency, it is observed that Mode 10 is excited on the piping system by the harmonic load, thereby creating a resonance. This can be seen graphically by plotting the mode shape corresponding to Mode 10 with frequency of “14.55 Hz” (figure shown on the left below) and the deflected shape for “harmonic response” case (figure shown on the right below). See snap shots for details.



Step 8:

In order to prevent piping failure due to resonance, it is important to suppress relevant modes by changing the stiffness of the piping system either by adding or by moving the existing piping supports. For example, for the layout shown above, a lateral restraint in X direction is added at Node 10 as the displacement in X direction is about 3" for Harmonic Response case prior to adding this X restraint. By adding this new support, the stiffness of the piping system is altered. This, in turn, removed the 10th frequency with "14.55 Hz", thereby ensuring that the natural frequency of the piping system is not close to the operating equipment frequency. See snap shots below.

